

NAG C Library Function Document

nag_ztbsv (f16skc)

1 Purpose

nag_ztbsv (f16skc) solves a system of equations given as a complex triangular band matrix.

2 Specification

```
#include <nag.h>
#include <nagf16.h>

void nag_ztbsv (Nag_OrderType order, Nag_UploType uplo, Nag_TransType trans,
               Nag_DiagType diag, Integer n, Integer k, Complex alpha, const Complex ab[],
               Integer pdab, Complex x[], Integer incx, NagError *fail)
```

3 Description

nag_ztbsv (f16skc) performs one of the matrix-vector operations

$$x \leftarrow \alpha A^{-1}x, \quad x \leftarrow \alpha A^{-T}x \quad \text{or} \quad x \leftarrow \alpha A^{-H}x,$$

where A is an n by n complex triangular band matrix with k subdiagonals or superdiagonals, x is an n element complex vector and α is a complex scalar. A^{-T} denotes $(A^T)^{-1}$ or equivalently $(A^{-1})^T$; A^{-H} denotes $(A^H)^{-1}$ or equivalently $(A^{-1})^H$.

No test for singularity or near-singularity of A is included in this function. Such tests must be performed before calling this function.

4 References

The BLAS Technical Forum Standard (2001) www.netlib.org/blas/blast-forum

5 Arguments

- 1: **order** – Nag_OrderType *Input*
On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order = Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this argument.
Constraint: **order = Nag_RowMajor** or **Nag_ColMajor**.
- 2: **uplo** – Nag_UploType *Input*
On entry: specifies whether A is upper or lower triangular.
uplo = Nag_Upper
 A is upper triangular.
uplo = Nag_Lower
 A is lower triangular.
Constraint: **uplo = Nag_Upper** or **Nag_Lower**.
- 3: **trans** – Nag_TransType *Input*
On entry: specifies the operation to be performed.

trans = Nag_NoTrans

$$x \leftarrow \alpha A^{-1}x.$$

trans = Nag_Trans

$$x \leftarrow \alpha A^{-T}x.$$

trans = Nag_ConjTrans

$$x \leftarrow \alpha A^{-H}x.$$

Constraint: **trans = Nag_NoTrans, Nag_Trans or Nag_ConjTrans.**

4: **diag** – Nag_DiagType *Input*

On entry: specifies whether A has non-unit or unit diagonal elements.

diag = Nag_NonUnitDiag

The diagonal elements are stored explicitly.

diag = Nag_UnitDiag

The diagonal elements are assumed to be 1 and are not referenced.

Constraint: **diag = Nag_NonUnitDiag or Nag_UnitDiag.**

5: **n** – Integer *Input*

On entry: n , the order of the matrix A .

Constraint: $n \geq 0$.

6: **k** – Integer *Input*

On entry: k , the number of subdiagonals or superdiagonals of the matrix A .

Constraint: $k \geq 0$.

7: **alpha** – Complex *Input*

On entry: the scalar α .

8: **ab**[*dim*] – const Complex *Input*

Note: the dimension, *dim*, of the array **ab** must be at least $\max(1, \mathbf{pdab} \times \mathbf{n})$.

On entry: the n by n triangular band matrix A . This is stored as a notional two-dimensional array with row elements or column elements stored contiguously. The storage of elements a_{ij} depends on the **order** and **uplo** arguments as follows:

if **order = Nag_ColMajor** and **uplo = Nag_Upper**,
 a_{ij} is stored in **ab**[$k + i - j + (j - 1) \times \mathbf{pdab}$],
 for $j = 1, \dots, n$ and $i = \max(1, j - k), \dots, j$;
 if **order = Nag_ColMajor** and **uplo = Nag_Lower**,
 a_{ij} is stored in **ab**[$i - j + (j - 1) \times \mathbf{pdab}$],
 for $j = 1, \dots, n$ and $i = j, \dots, \min(n, j + k)$;
 if **order = Nag_RowMajor** and **uplo = Nag_Upper**,
 a_{ij} is stored in **ab**[$j - i + (i - 1) \times \mathbf{pdab}$],
 for $i = 1, \dots, n$ and $j = i, \dots, \min(n, i + k)$;
 if **order = Nag_RowMajor** and **uplo = Nag_Lower**,
 a_{ij} is stored in **ab**[$k + j - i + (i - 1) \times \mathbf{pdab}$],
 for $i = 1, \dots, n$ and $j = \max(1, i - k), \dots, i$.

- 9: **pdab** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix A in the array **ab**.
Constraint: $\mathbf{pdab} \geq \mathbf{k} + 1$.
- 10: **x[*dim*]** – Complex *Input/Output*
Note: the dimension, *dim*, of the array **x** must be at least $\max(1, 1 + (\mathbf{n} - 1)|\mathbf{incx}|)$.
On entry: the vector x .
On exit: the solution vector x .
- 11: **incx** – Integer *Input*
On entry: the increment in the subscripts of **x** between successive elements of x .
Constraint: $\mathbf{incx} \neq 0$.
- 12: **fail** – NagError * *Input/Output*
The NAG error argument (see Section 2.6 of the Essential Introduction).

6 Error Indicators and Warnings

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

On entry, $\mathbf{incx} = \langle value \rangle$.

Constraint: $\mathbf{incx} \neq 0$.

On entry, $\mathbf{k} = \langle value \rangle$.

Constraint: $\mathbf{k} \geq 0$.

On entry, $\mathbf{n} = \langle value \rangle$.

Constraint: $\mathbf{n} \geq 0$.

NE_INT_2

On entry, $\mathbf{pdab} = \langle value \rangle$, $\mathbf{k} = \langle value \rangle$.

Constraint: $\mathbf{pdab} \geq \mathbf{k} + 1$.

7 Accuracy

The BLAS standard requires accurate implementations which avoid unnecessary over/underflow (see Section 2.7 of The BLAS Technical Forum Standard (2001)).

8 Further Comments

None.

9 Example

Solves complex triangular banded system of linear equations, $Ax = y$, where A is a complex triangular 4 by 4 matrix, with 2 subdiagonals, given by

$$A = \begin{pmatrix} -1.94 + 4.43i & & & & & \\ -3.39 + 3.44i & 4.12 - 4.27i & & & & \\ 1.62 + 3.68i & -1.84 + 5.53i & 0.43 - 2.66i & & & \\ & -2.77 - 1.93i & 1.74 - 0.04i & 0.44 + 0.10i & & \end{pmatrix}$$

and

$$y = \begin{pmatrix} -8.86 - 3.88i \\ -15.57 - 23.41i \\ -7.63 + 22.78i \\ -14.74 - 2.40i \end{pmatrix}.$$

9.1 Program Text

```

/* nag_ztbsv (f16skc) Example Program.
 *
 * Copyright 2005 Numerical Algorithms Group.
 *
 * Mark 8, 2005.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf16.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Complex alpha;
    Integer exit_status, i, incx, j, kd, n, pdab, xlen;

    /* Arrays */
    Complex *ab=0, *x=0;
    char nag_enum_arg[40];

    /* Nag Types */
    NagError fail;
    Nag_OrderType order;
    Nag_TransType trans;
    Nag_UploType uplo;
    Nag_DiagType diag;

#ifdef NAG_COLUMN_MAJOR
#define AB_UPPER(I,J) ab[(J-1)*pdab + kd + I - J]
#define AB_LOWER(I,J) ab[(J-1)*pdab + I - J]
#define B(I,J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define AB_UPPER(I,J) ab[(I-1)*pdab + J - I]
#define AB_LOWER(I,J) ab[(I-1)*pdab + kd + J - I]
#define B(I,J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    exit_status = 0;
    INIT_FAIL(fail);

    Vprintf( "nag_ztbsv (f16skc) Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[\n] ");

    /* Read the problem dimensions */
    Vscanf("%ld%ld%*[\n] ", &n, &kd);

```

```

/* Read the uplo storage parameter */
Vscanf("%s%*[\n] ", nag_enum_arg);
/* nag_enum_name_to_value(x04nac).
 * Converts NAG enum member name to value
 */
uplo = nag_enum_name_to_value(nag_enum_arg);
/* Read the transpose parameter */
Vscanf("%s%*[\n] ", nag_enum_arg);
/* nag_enum_name_to_value(x04nac), see above. */
trans = nag_enum_name_to_value(nag_enum_arg);
/* Read the unit-diagonal parameter */
Vscanf("%s%*[\n] ", nag_enum_arg);
/* nag_enum_name_to_value(x04nac), see above. */
diag = nag_enum_name_to_value(nag_enum_arg);

/* Read scalar parameters */
Vscanf(" ( %lf , %lf )%*[\n] ", &alpha.re, &alpha.im);
/* Read increment parameter */
Vscanf("%ld%*[\n] ", &incx);

pdab = kd + 1;
xlen = MAX(1, 1 + (n - 1)*ABS(incx));

if (n > 0)
{
    /* Allocate memory */
    if ( !(ab = NAG_ALLOC(pdab*n, Complex)) ||
        !(x = NAG_ALLOC(xlen, Complex)))
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
}
else
{
    Vprintf("Invalid n\n");
    exit_status = 1;
    return exit_status;
}

/* Input matrix AB and vector x*/
if (uplo == Nag_Upper)
{
    for (i = 1; i <= n; ++i)
    {
        if (diag == Nag_NonUnitDiag)
            Vscanf(" ( %lf , %lf )", &AB_UPPER(i,i).re,
                &AB_UPPER(i,i).im);
        for (j = i+1; j <= MIN(i+kd,n); ++j)
            Vscanf(" ( %lf , %lf )", &AB_UPPER(i,j).re,
                &AB_UPPER(i,j).im);
    }
    Vscanf("%*[\n] ");
}
else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = MAX(1,i-kd); j < i; ++j)
            Vscanf(" ( %lf , %lf )", &AB_LOWER(i,j).re,
                &AB_LOWER(i,j).im);
        if (diag == Nag_NonUnitDiag)
            Vscanf(" ( %lf , %lf )", &AB_LOWER(i,i).re,
                &AB_LOWER(i,i).im);
    }
    Vscanf("%*[\n] ");
}
for (i = 0; i < xlen; ++i)
    Vscanf(" ( %lf , %lf )%*[\n] ", &x[i].re, &x[i].im);

```

```

/* nag_ztbsv(f16skc).
 * Solution of complex triangular band system of linear equations.
 *
 */
nag_ztbsv(order, uplo, trans, diag, n, kd, alpha, ab, pdab, x, incx,
          &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from nag_ztbsv.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print output vector x */
Vprintf("%s\n", " Solution x:");
for (i = 0; i < xlen; i = ++i)
{
    Vprintf("( %11f , %11f )\n", x[i].re, x[i].im);
}

END:
if (ab) NAG_FREE(ab);
if (x) NAG_FREE(x);

return exit_status;
}

```

9.2 Program Data

```

nag_ztbvs (f16skc) Example Program Data
4 2                               :Value of n and kd
Nag_Lower                         :Storage of A
Nag_NoTrans                       :Transpose A?
Nag_NonUnitDiag                   :Unit diagonal elements?
( 1.0, 0.0)                       :Value of alpha
1                                  :Value of incx
(-1.94, 4.43)
(-3.39, 3.44) ( 4.12,-4.27)
( 1.62, 3.68) (-1.84, 5.53) ( 0.43,-2.66)
(-2.77,-1.93) ( 1.74,-0.04) ( 0.44, 0.10) :End of matrix A
( -8.86, -3.88)
(-15.57,-23.41)
( -7.63, 22.78)
(-14.74, -2.40)                   :End of vector x

```

9.3 Program Results

nag_ztbvs (f16skc) Example Program Results

```

Solution x:
( 0.000000 , 2.000000 )
( 1.000000 , -3.000000 )
( -4.000000 , -5.000000 )
( 2.000000 , -1.000000 )

```
